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From Voxels to Knowledge: A Practical Guide to the Segmentation of Complex Electron Microscopy 3D-Data *Wen-Ting Tsai (1), Ahmed Hassan (1), Purbasha Sarkar (2), Joaquin Correa (1) (3), Zoltan Metlagel (1), Danielle M. Jorgens (1), Manfred Auer (1) (2)*

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Automated segmentation of bacteria This example shows a method to perform 2D segmentation of bacteria using VLFEAT and MATLAB's Image Processing Toolbox.

bact_seg.m The parameters used are example specific

in_dir Work directory rad Margin nbins Number of bins thr Background threshold Corr Correction factor (Corr) di Correction factor (di) LS Correction factor (LS) bgd_area_th Background area for im opening cell_area_th_low Cell area low cell_area_th_high Cell area high rad_s Estimated cell radii thr_pb Theshold for prob map

```
function all_ims = bact_seg(in_dir, rad, nbins, thr, Corr, di, LS, bgd_area_th, cell_area_th_low, cell_area_th_high, rad_s, thr_pb)
```

Step 1: VLFEAT

Add the VLFeat Toolbox to MATLAB path. For more information visit [VLFEAT MATLAB API](#)

```
addpath vlfeat-0.9.14/toolbox
vl_setup
```

Step 2: Set the work directory

The images are stored in the JovE/images directory, in this example TIFF images will be processed.

```
% Clear workspace
% clear all; close all; clc

D = dir(fullfile(in_dir, '*.tif'));
```

Step 3: Script parameters

The user can specify a different background threshold value if needed, or multiple threshold values for independent images.

```
% For N images with independant background threshold |thr| should be:
% thr = [thr1 thr2 thr3 thrN]
% and |im = di*(Corr*or-thr)-LS| should be:
% im = di*(Corr*or-thr(i))-LS

% Margin
% rad = 3;

% Number of bins
% nbins = 4;

% Pre-image background threshold
% thr = 0;

% CValues
% Corr = 0.9;
% di = 1;
% LS = 0;
```

Step 4: Histogram collection and distance matrix with custom kernel

$K : 2 * \text{sum}(X .* Y) ./ (X + Y)$

```
all_ims = cell(numel(D), 1);
for i = 1 : numel(D),
```

```
    im = imread(fullfile(in_dir, D(i).name));

    %   im = imadjust(im);
    im = im2double(im);

    % for RGB images
    % im = im2double(rgb2gray(im));

    % if resize is required
    % im = imresize(im, 1);

    or = im;
```

Use Otsu's method if gives better result for l estimation thr = graythresh(or);

```
    im = di*(Corr*or-thr)-LS;
    im = max(min(1, im), 0);

    figure; title(D(i).name); imshow(im, 'Border', 'tight'); drawnow

    hh = histc(im(:), 0.001:0.001:1);
```

```
figure; bar(hh);
```

Collect histograms

```
hists = zeros(numel(im), nbins);
cnt = 0;
idx = zeros(size(im));

for x = rad+1 : size(im,1) - rad,
    for y = rad+1 : size(im,2) - rad,
        patch = im(x-rad:x+rad, y-rad:y+rad);
        cnt = cnt + 1;
        hists(cnt,:) = histc(patch(:), 0:1/nbins:1-1/nbins);
        idx(x, y) = cnt;
    end
end
hists = hists(1:cnt, :);
sm = sum(hists,2);
sm2 = repmat(sm, [1,size(hists,2)]);
hists = hists./(sm2 + (sm2==0));
```

Define exemplars

```
exemplars = eye(nbins);
dst_all = vl_alldist2(exemplars', hists', 'KCHI2');
```

Store results as a cell type array with multiple properties such as image (im), name, prob1, prob2 and prob3

```
all_ims{i}.im = im;
all_ims{i}.name = D(i).name(1:end-4);

cell_proba = dst_all(1, :);
idx2=idx;
idx2(idx==0)=numel(cell_proba)+1;
cell_proba(numel(cell_proba)+1)=0;
cell_proba=cell_proba(idx2);
all_ims{i}.proba1=cell_proba;

cell_proba = dst_all(2, :);
idx2=idx;
idx2(idx==0)=numel(cell_proba)+1;
cell_proba(numel(cell_proba)+1)=0;
cell_proba=cell_proba(idx2);
all_ims{i}.proba2=cell_proba;

cell_proba = dst_all(3, :);
idx2=idx;
idx2(idx==0)=numel(cell_proba)+1;
cell_proba(numel(cell_proba)+1)=0;
cell_proba=cell_proba(idx2);
all_ims{i}.proba3=cell_proba;
```

Probability map

```
figure; imshow(all_ims{1,1}.proba2), colormap(jet)
truesize
```

```
end
```

Step 5: Save results

Save all_ims

```
save hist_s_JoVe.mat all_ims
```

Step 6: Segmentation

```
rad2 = rad_s + 1;

out_dir = 'JoVe/results';
mkdir(out_dir);

str = strel(fspecial('disk', rad_s));
str2 = strel(fspecial('disk', rad2));

for i = 1 : numel(all_ims),

    im = all_ims{i}.im;
    figure;imshow(im, 'Border', 'tight'); drawnow
    figure;imshow(all_ims{i}.proba2, 'Border', 'tight'); colormap(jet); drawnow

    % Write initial cell probability map
    cell_proba = all_ims{i}.proba2;
    imwrite(cell_proba, fullfile(out_dir, [all_ims{i}.name '.png']));

    % Find max labeling and background
    probas = all_ims{i}.proba1;
    probas = cat(3, probas, cell_proba);
    probas = cat(3, probas, all_ims{i}.proba3);
    [vl labels]= max(probas, [], 3);
    bgd = labels~=2;
    bgd = bwareaopen(bgd, bgd_area_th);

    % Find cells
    fg = ~bgd;
    op = imopen(fg, str);
    er = imerode(op, str2);
    lbl = bwlabel(er);

    dl = imdilate(lbl, str);
    R = regionprops(dl, 'Area');
    for r = 1: numel(R),
        if (R(r).Area < cell_area_th_low) || (R(r).Area > cell_area_th_high),
            dl(dl==r) = 0;
        end
    end
end
```

```

        end
    end
    dl = cmunique(dl);

    nb_cells = max(dl(:));
    bdry = seg2bdry(dl, 'imageSize');

    % Find metal deposits
    metal = (labels==1);
    lmet = bwlabel(metal);
    fr = false(size(metal)); fr(1:5,:)=true; fr(:,1:5)=true; fr(end-4:end,:)=true; fr(:,end-4:
end)=true;
    for m =1:max(lmet(:)),
        bw = (lmet==m) &fr;
        if max(bw(:))==1,
            metal(lmet==m)=0;
        end
    end
end

% Find other features
dl( dl==0 & all_ims{i}.proba2>thr_pb) = nb_cells + 1;
dl(metal) = nb_cells+2;

% Results
mp = rand(nb_cells+3,3);mp(1,:)= [ 1 1 1];mp(end-1,:)= [0 0 0];mp(end,:)= [0 1 0];
Lrgb=ind2rgb(uint8(dl),mp);
figure;imshow(Lrgb,'Border','tight');

% Save seg
imwrite(all_ims{i}.im.*(fg), fullfile(out_dir, [strcat(all_ims{i}.name,'_bacteria') '.png'
]);
imwrite(all_ims{1}.im.*Lrgb(:,:,1), fullfile(out_dir, [strcat(all_ims{i}.name,'_metal') '.
png' ]));

% Display result overlaid on original image
figure, clf; imshow(im.*~bdry,'Border','tight'), hold on
himage = imshow(Lrgb,'Border','tight');
set(himage, 'AlphaData', 0.5)
drawnow;
end

```

end

```

function [ bdry ] = seg2bdry(seg, fmt)
    if nargin<2, fmt = 'imageSize'; end;

    if ~strcmp(fmt,'imageSize') && ~strcmp(fmt,'doubleSize'),
        error('possible values for fmt are: imageSize and doubleSize');
    end

    [tx, ty, nch] = size(seg);

    if nch ~=1,
        error('seg must be a scalar image');
    end
end

```

```

bdry = zeros(2*tx+1, 2*ty+1);

edgels_v = ( seg(1:end-1, :) ~= seg(2:end, :) );
edgels_v(end+1, :) = 0;
edgels_h = ( seg(:, 1:end-1) ~= seg(:, 2:end) );
edgels_h(:, end+1) = 0;

bdry(3:2:end, 2:2:end) = edgels_v;
bdry(2:2:end, 3:2:end) = edgels_h;
bdry(3:2:end-1, 3:2:end-1) = max ( max(edgels_h(1:end-1, 1:end-1), edgels_h(2:end, 1:end-1)
), max(edgels_v(1:end-1, 1:end-1), edgels_v(1:end-1, 2:end)) );

bdry(1, :) = bdry(2, :);
bdry(:, 1) = bdry(:, 2);
bdry(end, :) = bdry(end-1, :);
bdry(:, end) = bdry(:, end-1);

if strcmp(fmt, 'imageSize'),
    bdry = bdry(3:2:end, 3:2:end);
end
end

```