Automated Sample Multiplexing by using Combined Precursor Isotopic Labeling and Isobaric Tagging (cPILOT)

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comparable automation devices.

We have introduced a high throughput quantitative proteomics workflow, combined precursor isotopic labeling and isobaric tagging (cPILOT) capable of multiplexing

up to 22 or 24 samples with tandem mass tags or isobaric N,N-dimethyl leucine

isobaric tags, respectively, in a single experiment. This enhanced sample multiplexing

considerably reduces mass spectrometry acquisition times and increases the utility

of the expensive commercial isobaric reagents. However, the manual process of

sample handling and pipetting steps in the strategy can be labor intensive, time consuming, and introduce sample loss and quantitative error. These limitations can be

overcome through the incorporation of automation. Here we transferred the manual

cPILOT protocol to an automated liquid handling device that can prepare large sample

numbers (i.e., 96 samples) in parallel. Overall, automation increases feasibility and

reproducibility of cPILOT and allows for broad usage by other researchers with

Abstract

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Citation

Arul, A.B., Robinson, R.A. Automated Sample Multiplexing by using Combined Precursor Isotopic Labeling and Isobaric Tagging (cPILOT). *J. Vis. Exp.* (166), e61342, doi:10.3791/61342 (2020).

Date Published

December 18, 2020

DOI

10.3791/61342

URL

jove.com/video/61342

Introduction

Mass spectrometry (MS)-based proteomics is an indispensable research tool in identifying disease specific biomarkers, understanding disease progression, and creating leads for therapeutic development. This can be achieved from a range of disease-related clinical samples such as blood serum/plasma, proximal fluids, and tissues^{1,2}. Proteomics biomarker discovery and validation have recently gained significant consideration due to the power of sample multiplexing strategies^{3,4}. Sample multiplexing is a technique

that enables simultaneous comparison and quantification of two or more sample conditions within a single MS injection^{5,6}. Sample multiplexing is achieved by barcoding peptides or proteins from multiple samples with chemical, enzymatic, or metabolic tags and obtaining MS information from all samples in a single MS or MS/MS experiment. Among the available isobaric tags are isobaric tagging reagents (iTRAQ), commercial tandem mass tags (TMT), and in house

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synthesized isobaric N,N-dimethyl leucine (DiLeu) reagents with capabilities up to 16-plex⁷ and 21-plex⁸, respectively.

Combined precursor isotopic labeling and isobaric tagging (cPILOT) is an enhanced sample multiplexing technology. cPILOT combines isotopic labeling of peptide N-termini with light [-(CH₃)₂] and heavy [-(¹³C²H₃)₂] isotopes at low pH (#2.5), which keeps the lysine residue available for subsequent high pH (8.5) isobaric labeling using TMT, DiLeu, or iTRAQ tagging^{3,9,10,11,12,13,14}. The dual labeling scheme of the cPILOT strategy is depicted in Supplemental Figure 1 with two samples using an example peptide. The accuracy and precision of the TMT based quantification at the MS² level can be compromised due to the presence of contaminating co-isolated and co-fragmented ions termed as the interference effect¹⁵. This limitation in inaccurate reporter ion ratios can be overcome with the help of tribrid Orbitrap mass spectrometers. For example, the interference effect can be overcome by isolating a peak in a dimethylated pair at the MS¹ level in the mass spectrometer, subjecting the light or heavy peak to MS² fragmentation in the linear ion trap and then subjecting the most intense MS² fragment for HCD-MS³ to obtain quantitative information. In order to increase the chances of selecting the peptides without lysine amines available for generating reporter ions, a selective MS³ acquisition based on the y-1 fragment also can be used and is an approach which can result in a higher percentage of peptides quantifiable with cPILOT⁹. The combination of light and heavy labeling increases sample multiplexing capabilities by a factor of 2x to that achieved with individual isobaric tags. We have recently used cPILOT to combine up to 24 samples in a single experiment with DiLeu reagents¹⁶. Additionally cPILOT has been used to study oxidative posttranslational modifications¹⁴ including protein nitration¹⁷. other global proteomes⁹, and has demonstrated applications

across multiple tissue samples in an Alzheimer's disease mouse model¹¹.

Robust sample preparation is a critical step in a cPILOT experiment and can be time-consuming, laborious, and extensive. Enhanced sample multiplexing requires extensive pipetting and highly skilled laboratory personnel, and there are several factors that can heavily influence the reproducibility of the experiment. For example, careful handling of samples is necessary to ensure similar reaction times for all samples and to maintain appropriate buffer pH for light and heavy dimethylated samples. Furthermore, manual preparation of tens to hundreds of samples can introduce high experimental error. Therefore, to reduce sample preparation variability, improve quantitative accuracy. and increase experimental throughput, we developed an automated cPILOT workflow. Automation is achieved using a robotic liquid handling device that can complete many aspects of the workflow (Figure 1). Sample preparation from protein quantification to peptide labeling was performed on an automated liquid handler. The automated liquid handler is integrated with a positive pressure apparatus (PPA) for buffer exchanges between the solid-phase extraction (SPE) plates, orbital shaker, and a heating/cooling device. The robotic platform contains 28 deck locations to accommodate plates and buffers. There are two pods with a gripper to transfer the plates within the deck locations: a 96-channel fixed volume pipetting head (5-1100 µL) and 8 channel variable volume probes (1-1000 µL). The robotic platform is controlled using a software. The user needs to be professionally trained prior to using the robotic liquid handler. The present study focuses on automating the manual cPILOT workflow, which can be labor intensive for processing more than 12 samples in a single batch. In order to increase the throughput of the cPILOT approach¹¹, we transferred the cPILOT protocol to

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a robotic liquid handler to process more than 10 samples in parallel. The automation also allows similar reactions for each sample in parallel during various steps of the sample preparation process, which required highly trained users to achieve during manual cPILOT. This protocol focuses on the implementation of the automated liquid handling device to carry out cPILOT. The present study describes the protocol for using this automated system and demonstrates its performance using a 22-plex "proof-of-concept" analysis of mouse liver homogenates.

Protocol

All animal protocols were approved by the Institutional Animal Care and Use Committee at the University of Pittsburgh. One male control mouse (C57/BLJ) was purchased commercially and housed in the Division of Laboratory Animal Resources at the University of Pittsburgh. Mice were fed standard rodent laboratory chow ad libitum and kept in a 12 h light/dark cycle. Liver tissue was harvested and stored at -80 °C.

1. Protein extraction

NOTE: These steps are performed manually.

 Wash mouse liver (100 mg) with saline and homogenate with 500 µL of 8 M urea using a mechanical homogenizer using lysing matrix A beads for 4 m/s for 20 s.

NOTE: In this study, protease or phosphatase inhibitors were not added but may be added to the buffer if necessary, based on the experiment. Also, protein extraction steps can be adjusted accordingly for various sample types.

2. Transfer the tissue homogenate to a new microcentrifuge tube, rinse and combine the lysing tubes with 100-500 μ L of PBS with 8 M urea.

 Centrifuge the homogenized tissues (12,800 x g, 4 °C, and 15 min) and collect the supernatant.

NOTE: The rest of the steps are carried out on the robotic liquid handler available in the user's laboratory. The liquid handler must be capable of aspirating and dispensing buffers from and to ANCI specified plate's types, with minimal operator participation.

- Determine the protein concentration using a bicinchoninic acid (BCA) assay according to manufacturer's instructions.
- Turn on the PPA, heating/cooling device, and the vacuum pumps and connect all the accessories with liquid handler. The liquid handler shows a blue light once it is connected to the computer and ready to operate.
- To reagent plate 1 (96 well plate), add 30 μL of 25 mM 1,4-dithiothreitol (DTT), 25 mM 30 μL of cysteine and 25 mM 30 μL of iodoacetamide (IAA) to rows 1, 2, and 3, respectively.
- Add 8 M urea and 20 mM Tris with 10 mM CaCl₂ (pH 8.2) to a reservoir plate. Add 500 μL of 5% formic acid to 2 mL deep well plate, 20 μL of trypsin to row 1 of trypsin plate and place in the deck location as specified by the method.

NOTE: IAA and trypsin were added to the 96 well plate prior to adding to the sample.

Aliquot 300 μL of the liver homogenate into a 500 μL tube and place on a 2 mL deep well plate and place at 4 °C until the start of the protocol. For this experiment, 22 aliquots were generated from the single liver homogenate.

NOTE: Add an internal quality control standard (e.g., bovine alpha casein or other exogenous protein) with the ratio 1 µg standard: 100 µg protein sample.

 Define the volume of buffers to be added to the samples by variable names and value as per **Table 1**. Based on the BCA, enter the volume of sample and normalization buffer (8 M urea) on a spreadsheet and attach to the software (**Table 2**).

NOTE: Further dilution with buffer may be necessary if the protein concentration is too high. The resulting concentrations for sample from the liver tissue was 10 μ g/µL. The volume of buffers was optimized for 100 µg protein.

- Remove sample tubes from 4 °C, place on the specified deck location of the automated liquid handler, and allow to warm for 10 min.
- Open the method and follow the instructions to place the required tips (1070, 90, and 230 μL), and labware into the desired positions. Once all the labware and tips are in place, cross check with the final deck layout and click Next to continue the protocol.

NOTE: The guided set up informs the user to add a required volume of buffer to the specific labware depending on the protocol and the deck location to be kept.

2. Sample reduction, alkylation and digestion

 Load 230 µL tips and aspirate 90 µL of 8 M urea from the reservoir and dispense to row 1 of the black 2 mL deep well plate. Unload the tips. Repeat this step until 8 M urea is added to all the wells corresponding to the 22 samples. NOTE: The denaturation buffer unwinds the protein three-dimensional structure to yield the primary structure so the trypsin can act and break the protein effectively. The 8-channel pipette can aspirate different volumes for the 8 channels and can dispense to different locations in the labware. In this step all the channels aspirated the same volume as defined in the software.

- After adding the denaturation buffer, load the 90 µL tips and aspirate 10 µL (corresponds to 100 µg) of mouse liver homogenate using the 8-channel pipette to the black 2 mL deep well plate. Unload the tips. Repeat this step until all the 22 samples are transferred.
- After each transfer, perform a mix step to aspirate and dispense 50 µL of the well contents thrice to ensure mixing of the protein with the buffer to exhibit a 1:1 ratio. NOTE: Remove stock homogenate sample and place in -80 °C.
- To reduce the denatured proteins, load one row of 90 μL tips and aspirate 3 μL of DTT from the reagent plate 1.
 Dispense DTT to rows 1 and 2 of the black 2 mL deep well plate and unload the tips.

NOTE: The protein: DTT molar ratio is maintained at 1:40 for reduction of disulfide bonds. The calculation for the molar ratio is based off the protein mass of bovine serum albumin (BSA), which is 66.5×10^3 g/mol.

- Seal the sample plate with aluminum foil and incubate at 37 °C for 600 s at 300 rpm.
- Add 30 μL of 0.25 M IAM to row 3 of reagent plate 1 just before use and place on the deck. Unseal the sample plate and return to the deck.
 NOTE: IAM is light sensitive.
- Load one row of 90 µL tips, aspirate 6 µL of IAM from the reagent plate 1 at row 3, and dispense to row 1 of the sample plate. Unload the tips.

NOTE: The protein: IAM molar ratio is maintained at 1:80 for each sample. This reaction must be done in the dark.

 Seal the sample plate and incubate at 4 °C for 30 min at 300 rpm on the heating/cooling device. NOTE: Sealing the plate is performed to prevent the sample from light, evaporation and spilling from the well.

- Unseal the sample plate and load one row of 90 μL tips and aspirate 5 μL of cysteine from the reagent plate 1 at row 2. Dispense to rows 1 and 2 of the sample plate and unload the tips. Incubate at room temperature for 30 min. NOTE: The protein: L-cysteine molar ratio is maintained at 1:40.
- Place the sample plate on the orbital shaker to perform a timed shake of 1800 rpm for 30 min.
- Add 800 µL of 20 mM Tris buffer with 10 mM CaCl₂ (pH
 8.2) to each well of the sample plate to dilute the urea concentration to 2 M. Unload the tips.

NOTE: Trypsin activity is hindered at higher urea concentrations and hence it must be reduced to less than 2 M. This study was performed with a protein to trypsin molar ratio of 50: 1 for 14 h.

- Add 20 μL of trypsin to row 1, column 1-12 of a 96 well plate and place at a specified location on the deck.
- Load one row of 90 μL tips, aspirate 2 μL of trypsin from the trypsin plate row 1, and dispense to rows 1 and 2 of the sample plate. Unload the tips.
- Seal the plate and incubate for 14 h at 37 °C at 600 rpm on the heating/cooling device.
- After incubation, unseal the sample plate and add 5% formic acid to row 3, column 1- 12 of a deep well collection plate and place it on specified deck.
- Stop the digestion by adding 150 µL of 5% formic acid from row 3 of the formic acid plate and dispense to sample plate at rows 1 and 2. Unload the tips.

3. Desalting step 1

- Desalt the peptides with SPE plate containing 20 mg of Targa C-18 material. Fix the volume for every buffer exchange as 600 μL and fix the pressure to 100 mbar.
- Load 1070 µL tips and aspirate 600 µL of acetonitrile and dispense to rows 1 and 2 of SPE plate. Place the SPE plate on PPA and apply pressure.
- Using the same tips, aspirate 600 µL of acetonitrile and dispense to rows 1 and 2 of SPE plate. Place the SPE plate on PPA and apply pressure.
 NOTE: The flow-through can be drained to waste using a suction pump.
- 4. Load 1070 µL tips and aspirate 600 µL of Buffer A (100 % water in 0.1 % formic acid) and dispense to rows 1 and 2 of SPE plate. Place the SPE plate on PPA and apply pressure.

NOTE: If the volume of the buffer does not reduce significantly try increasing the pressure or time.

- Load 2 rows of 1070 μL tips, aspirate 534 μL of digested samples, and dispense to rows 1 and 2 of SPE plate. Place the SPE plate on PPA and apply pressure. Repeat this step until all the samples are loaded.
 NOTE: Since the total volume after adding formic acid will be 1068 μL and the samples were added in two passes.
- Load 2 rows of used 1070 μL tips, aspirate 600 μL of Buffer A, and dispense to rows 1 and 2 of SPE plate.
 Place the SPE plate on PPA and apply pressure.
- 7. Repeat the above step once to clean the sample.
- Load 1 row of 1070 μL tips, aspirate 600 μL of ACN: Water (60:40) and dispense to rows 1 and 2 of SPE plate.
 Place the SPE plate on top of a collection plate to elute the peptides using PPA and apply pressure.

 Repeat the above step to elute the peptides in the collection plate. Dry the collection plate to dryness and store at -80° C until further processing.

4. Dimethylation Labeling (peptide N-termini)

- Place the required tips (1070, 90, and 230 µL), and labware into the desired positions in the software. Once all the labware and tips are in place, cross check with the final deck layout and click **Next** to continue the protocol.
- To reagent plate 2, add 450 μL of 1% acetic acid, 50 μL light formaldehyde (CH₂O), 50 μL of heavy formaldehyde (¹³CD₂O), and 150 μL of formic acid to rows 1, 2, 3 and 4 respectively.
- 3. To reagent plate 3 add 50 μL of light CB, 50 μL of heavy CB, to rows 1 and 2 and 50 μL of Ammonia to row 3 and 4.
- 4. Load 2 rows of 230 μL tips and aspirate 100 μL of 1% acetic acid from row 1 of reagent plate 2 and dispense to the dried down peptides in sample plate 2 (collection plate from the desalting step) rows 1 and 2 and perform a timed shaking for 5 min at 1800 rpm.
- Load 90 μL tips and aspirate 16 μL of 60 mM (4%) CH₂O (37% wt/v) from row 2 of reagent plate 2 and dispense to row 1 of the sample plate. Unload the tips.
- Load 1 row of 90 μL tips and aspirate 16 μL of 60 mM (4%) ¹³CD₂O (20% wt/v) from row 3 of reagent plate 2 and dispense to row 2 of the sample plate. Unload the tips.

NOTE: In this study row 1 corresponds to light and row 2 corresponds to heavy dimethylated samples (See Figure 1).

 Load 2 rows of 90 µL tips and aspirate 16 µL of 24 mM NaBH₃CN and 24 mM NaBD₃CN from row 1 and 2 of reagent plate 3 and dispense to rows 1 and 2, respectively of the sample plate.

- 8. Unload the tips and perform a timed shake for 15 min at 1800 rpm using the orbital shaker.
 NOTE: Adding sodium cyanoborohydride initiates the reaction hence to reduce variability between experiments this step is performed once per batch.
- Load 2 row of 90 µL tips and aspirate 32 µL of 1% ammonia (~28-30% v/v) from rows 3 and 4 of reagent plate 3 and dispense to rows 1 and 2 respectively of the sample plate 2. Unload the tips.

NOTE: Adding ammonia stops the reaction hence to reduce variability between experiments this step is performed once per batch.

 Combine equal volumes of light and heavy (1:1) dimethylated peptides to a new 2 mL deep well plate for desalting.

NOTE: In this study 90 μ L of the well contents from row 1 was combined with 90 μ L of row 2 from sample plate 2 to a new 2 mL collection plate (Sample Plate 3). The ratio of light: heavy mixing depends on the experimental protocol, in this study a 1:1 ratio was used.

 Load 2 rows of 230 µL tips and aspirate 32 µL of 5% formic acid to the combined samples and perform a timed shaking for 30 s at 1800 rpm.

NOTE: The dimethylation efficiency depends on the pH of the reaction mixture and any change in buffer pH will result in incomplete labeling of the peptide N-termini. Dimethylation efficiency should be greater than 97% when searched as dynamic modification at the peptide N-termini. In this study the labeling efficiency of light and heavy peptides were 99.7% and 99.5% respectively.

5. Desalting step 2

- Perform sample desalting similar to the desalt step 1 for the combined samples.
- Dry the samples in the sample plate using a speed vac and store at -80 °C until further processing.

6. Isobaric tagging (Lys residues)

- Follow the guided labware setup and place the required tips (1070, 90, and 230 µL), with appropriate buffers. Once all the labware and tips are in place, cross check with the final deck layout and click **Next** to continue the protocol.
- Add 250 µL of 100 mM triethyl ammonium bicarbonate (TEAB), 30 µL of hydroxylamine (10% w/v) to rows 1, and
 2 of reagent plate 4. Place the TMT tubes on the 2 mL deep-well plate as per the spreadsheet in Table 3.
- Keep an empty 1.5 mL tube in a tube rack holder for pooling the tagged peptides. Place the dried down sample plate at P9 and TMT processing plate at P14.
- 4. To reconstitute the peptides, load 230 μL tips and aspirate 100 μL of 100 mM triethyl ammonium bicarbonate (TEAB) buffer (pH ~8.5) from row 1 at TEAB plate and dispense to the dried peptides at row 3 of sample plate 3. Place the plate on the orbital shaker for 30 s at 1800 rpm.

NOTE: Reconstitute 100 μ g of dimethylated peptides at a concentration of 1 μ g/ μ L.

- 5. Load 90 μ L tips and aspirate 10 μ L of anhydrous acetonitrile from H12 of the TMT plate and dispense into each of the dried TMT tubes.
- 6. Remove the TMT tubes, vortex, and quick spin the tubes and return to deck in deep well plate.

- 7. Load 1 row of 90 μL tips and aspirate 12.5 μL of the combined dimethylated peptides and dispense to the row 1 of the TMT processing plate. Unload the tips.
 NOTE: The TMT: peptide ratio was maintained at 1:8 for this experiment.
- Load 1 row of 90 μL tips and aspirate 10 μL of TMT and dispense to the row 1 of the TMT processing plate. Unload the tips, perform a timed shake for 1 hour at 1800 rpm.
- Load 1 row of 90 μL tips and aspirate 8 μL of hydroxylamine (10% w/v) from row 2 at TEAB plate and dispense to the row 1 of the TMT processing plate. Unload the tips, perform a timed shaking for 15 min at 1800 rpm.
- Combine 30.5 μL of the TMT labeled peptides from TMT processing plate to 1.5 mL tube. Unload the tips after each transfer.
- 11. Remove the tube with the pooled samples and dry to evaporate the acetonitrile. Reconstitute peptides in 0.2 mL of water in 0.1 % formic acid and return to the deck. NOTE: The labeling efficiency of isobaric tagging is also pH specific and the labeling efficiency should be above 98% per manufacturer's instructions. In this study the TMT labeling efficiency of the lysine terminated light and heavy peptides was 99.4% and 99.5% respectively.

7. Desalting step

- Perform sample desalting similar to the desalt 1 for one sample.
- 2. Dry the samples and store in -80 °C until analysis.

8. Liquid Chromatography–Tandem Mass Spectrometry (LC-MS/MS) and MS³

 Reconstitute the peptides in MS grade water with 0.1% FA to obtain ~1 μg/μL concentration. Filter samples with microcentrifuge tubes containing a 0.65 μm filter. Centrifuge peptides at 12,000 x g for 3 min and place the flow through into an auto-sampler vial.

NOTE: The peptide concentration can be confirmed at this stage if desired. The peptides would need to be reconstituted in LC-MS grade water and subject to a BCA peptide assay. In this study, the peptide BCA assay was not performed and all peptide amounts were based on initial protein BCA assay.

- 2. Prepare the mobile phase buffers as follows: 100% (v/v) water with 0.1% FA (A) and 100% ACN with 0.1% FA (B).
- Inject 1 μL of sample onto a trap column packed with 2 cm of C₁₈ material (3 μm, 100 Å pore size).
 NOTE: Sample cleaning on the trap is as follows: 10 min, 100% A; 2 μL/min using a 2D liquid chromatography system.
- 4. Run the analytical separation method. Use a 100 μ m i.d. x 26 cm laser pulled-tip fused silica capillary column packed with C₁₈ material (2.5 μ m, 100 Å). The gradient is: 0-10 min, 10% B; 10-30 min, 10-15% B; 30-75 min, 15-30% B; 75-88 min, 30-60% B; 88-92 min, 60-90% B; 92-99 min, 90% B; 99-100 min, 90-10% B, 100-120 min, 10% B; 300 nL/min, 120 min.
- Run the data acquisition for the mass spectrometer while the analytical separation method is running.
 - 1. Use the following parameters for the MS survey scan: 375-1,500 *m/z*, 120,000 resolution, Cycle time

3 s (top speed), automatic gain control (AGC) target4.0e5, maximum injection time 50 ms.

- Use the following parameters for CID–MS/MS with ion trap: data dependent acquisition (DDA) scans per outcome, 2 m/z isolation width, 35% normalized collision energy (NCE), 0.25 activation q, 10 ms activation time, 1.0e4 AGC, 100 ms maximum injection time.
- Use the following parameters for HCD–MS3 SPS 10: Scan range 100-400 *m/z*, number of dependent scans 10, AGC 5.0e4, maximum injection time 118 ms, HCD collision energy 55%, MS² isolation window 2.

9. Data analysis

 Search generated RAW files for the list of proteins and peptides using a protein analysis software against an appropriate database.

NOTE: The RAW files generated in this study were searched against a mouse Uniprot database.

- Since there is both light and heavy labeling in one RAW file, search each file with two workflows for light and heavy dimethylated peptides.
- Search the RAW files against mouse Uniprot database (07/13/2019) with 53035 sequence with the following parameters: trypsin cleavage with maximum two missed cleavages, peptide with minimum 6 amino acids length, 15 ppm parent mass tolerance, 1 Da fragmentation tolerance Static modifications: light dimethylation (+28.031, peptide N-terminus) or heavy dimethylation (+36.076 Da, peptide N-terminus), carbamidomethyl (+57.021 Da, C), Dynamic modifications: oxidation (+15.995 Da, M), 11-plex isobaric tag (229.163 Da,

K), 1% FDR, reporter ion quantification with 30 ppm peak integration tolerance, most confident centroid for integration method.

NOTE: The heavy dimethylated peak also includes another modification which is ~7 Da (+35.069 Da, peptide N-terminus) from the light dimethylated peak and therefore another search node should be incorporated to include this modification also.

 Perform reporter ion quantification based on the intensity, 65% SPS mass match, average S/N ratio 10, isotopic correction, normalization and scaling were not performed.

NOTE: Normalization and scaling can be performed based on total peptide amount or a specific protein added to the sample. QC samples can also be included in the channels for inter-batch or intra-batch normalization based on a two-tailed internal reference scaling¹⁸. The isotopic contaminations of different TMT channels were not provided to the search, users are advised to add the isotope contamination of different reporter ions.

Representative Results

Figure 2 shows representative MS data of a peptide identified in all 22 reporter ion channels from a 22-plex cPILOT experiment, including workflow replicates. **Figure 2** (top) depicts a doubly charged peak pair separated by 4 Da m/zz spacing indicating a single dimethyl group incorporated

into the peptide. The light and heavy dimethylated peak pairs were isolated and fragmented independently to yield the sequence of the peptide. The sequence of the peptide is G(dimethyl)AAELMQQK(TMT-11plex) and corresponds to the protein Betaine-homocysteine S-methyl transferase. The most intense fragment ions for both the light and heavy dimethylated peaks (*not shown*) were further isolated for MS^3 fragmentation and the reporter ions (m/z 126-131) are shown in Figure 2 (bottom). The reporter ion intensities are directly proportionate to the peptide abundance in the sample. The peptide abundance of the samples implies the pipetting ability of the robotic platform is fairly uniform across the 22 samples. Overall, this 22-plex cPILOT experiment resulted in 1326 (1209-light/1181-heavy) proteins identifications resulting from 3098 (6137-light/5872-heavy) peptides (Table 4). Figure 3 shows the box plot of log10 abundance versus total reporter ion intensities across all the 22 channels showing lesser inter-well/inter-sample variability. Evaluation of the total automation was done by examining the error in reporter ion abundance across each protein in the 22 samples. Figure 4 shows that sample processing with the robotic platform resulted in very low CV values. Specifically, across the 3098 peptides identified the average CV in reporter ion abundance was 12.36 % and 15.03 % for light and heavy dimethylated peptides, respectively. Among these peptides 2032 of these peptides had reporter ion signal above the minimum threshold and were deemed quantifiable.



Figure 1. Experimental workflow to process 22 samples in parallel with an automated cPILOT protocol. Please click

here to view a larger version of this figure.



Figure 2. Quantification of peptides across 22 samples. Example MS (top) and MS³ (bottom) spectra of the peptide G(dimethyl)AAELMQQK(TMT-11plex) quantified in 22-plex automated cPILOT experiment for light dimethylated (bottom left) and heavy dimethylated (bottom right) peaks. Please click here to view a larger version of this figure.



Figure 3. Box plot of total reporter ion intensities versus log10 abundance of 22 samples using proteome discoverer

2.3. The RAW file was searched twice for light and heavy peptides, proteins IDs separately with TMT as dynamic modification, light (+28.031 Da) and heavy (+36.076 & +35.069 Da) dimethylation at peptide N-termini as static modification. A combined search with all the above modifications was run using Proteome Discover 2.3 to obtain the Log 10 Abundance of peptide intensities across all the channels. Please click here to view a larger version of this figure.



Figure 4. Violin plots of co-efficient of variation of peptide abundance from summed reporter ion intensities across channels 126-131 *m*/*z*. The peptide was quantified with an average CV value of 12.36 and 15.03 for light (2373) and heavy (2533) quantifiable peptides. Please click here to view a larger version of this figure.

Supplemental Figure 1. Illustration of the cPILOT with a single peptide. Showing the isotopic labeling of two different samples and isobaric tagging with TMT¹²⁶, the resulting mixture was injected to MS for LC-MS³. Please click here to download this file.

Variable Name	Value	Description		
DesaltSamp1	1065	Volume to be used for desalt step 1		
DesaltSamp2	392	Volume to be used for desalt step 2		
DesaltSamp3	100	Volume to be used for desalt step 3		
DevMode	FALSE	False will cut-down the incubation		
		times to 30sec- True will follow the		
		incubation timing in the protocol.		
DTTVol	3	Volume of DTT		
FilterPlate	Targa	Plate used for desalting		
FilterPlateVol	600	Volume for desalting		

HAWaterWashes	FALSE	Number of water washes	
		on the SPE plate	
IAMVol	2	Volume of iodoacetamide	
PeptideTMTVol	12.5	Volume of peptide for TMT labelling	
pressure	100	mbar pressure at PPA	
TempOffSet	1	Change in temperature	
TMTVol	10	Isobaric tag volume to be added	
TrisVol	800	Volume to dilute sample	
		prior to digestion	
TrypsinVol	2	Volume of trypsin	
UsePopTimer	TRUE	True displays the options to apply	
		pressure on plate if required	

Table 1. List of variables used in automated cPILOT protocol.

DilSource	DilWell	Dest	DestWell	DilVolume	StockSource	StockWell	SampleVol	SampleID
8M_Urea	1	Samples	A1	90	Stock_Sample	s A1	10	1
8M_Urea	1	Samples	A2	90	Stock_Sample	s A1	10	2
8M_Urea	1	Samples	A3	90	Stock_Sample	s A1	10	3
8M_Urea	1	Samples	A4	90	Stock_Sample	s A1	10	4
8M_Urea	1	Samples	A5	90	Stock_Sample	s A1	10	5
8M_Urea	1	Samples	A6	90	Stock_Sample	s A1	10	6
8M_Urea	1	Samples	A7	90	Stock_Sample	s A1	10	7
8M_Urea	1	Samples	A8	90	Stock_Sample	s A1	10	8
8M_Urea	1	Samples	A9	90	Stock_Sample	s A1	10	9
8M_Urea	1	Samples	A10	90	Stock_Sample	s A1	10	10
8M_Urea	1	Samples	A11	90	Stock_Sample	s A1	10	11
8M_Urea	1	Samples	A12	90	Stock_Sample	s A1	10	12
8M_Urea	1	Samples	B1	90	Stock_Sample	s A1	10	13
8M_Urea	1	Samples	B2	90 \$	Stock_Sample	s A1	10	14
8M_Urea	1	Samples	B3	90 :	Stock_Sample	s A1	10	15
8M_Urea	1	Samples	B4	90	Stock_Sample	s A1	10	16
8M_Urea	1	Samples	B5	90	Stock_Sample	s A1	10	17
8M_Urea	1	Samples	B6	90 \$	Stock_Sample	s A1	10	18
8M_Urea	1	Samples	B7	90	Stock_Sample	s A1	10	19
8M_Urea	1	Samples	B8	90	Stock_Sample	s A1	10	20
8M_Urea	1	Samples	B9	90	Stock_Sample	s A1	10	21
8M_Urea	1	Samples	B10	90	Stock_Sample	s A1	10	22
8M_Urea	1	Samples	B11	90	Stock_Sample	s A1	10	23
8M_Urea	1	Samples	B12	90	stock_Sample	s A1	10	24

Table 2. Volume of mouse liver homogenate and 8 M urea.

SourceWell	SourceWell2	Reporter Ion	DestWell1	DestWell2	Volume	SampleID
A1	C1	126	A1	E1	10	1
A3	C3	127N	A2	E2	10	2
A5	C5	127C	A3	E3	10	3
A7	C7	128N	A4	E4	10	4
A9	C9	128C	A5	E5	10	5
A11	C11	129N	A6	E6	10	6
B2	D2	129C	A7	E7	10	7
B4	D4	130N	A8	E8	10	8
B6	D6	130C	A9	E9	10	9
B8	D8	131N	A10	E10	10	10
B10	D10	131C	A11	E11	10	11

Table 3. Total number of peptides, proteins and peptide spectral matches (PSMs).

	Automated cPILOT		
	Light	Heavy	
Proteins	1209	1181	
Peptides	6137	5872	
PSMs	14948	16762	

Table 4. Barcoding the isobaric tags with the light and heavy labelled samples.

Discussion

cPILOT is an enhanced multiplexing strategy that can analyze up to 24 samples in a single experiment. The multiplexing capacity depends on the number of available isotopic and isobaric tagging combinations. Introduction of the TMTpro⁷, which is capable of tagging 16 samples in single experiment, can push the limits of cPILOT to 32-plex. cPILOT consists of multiple pipetting steps and requires extensive care and user skills to perform sample preparation. Even with an expert user, manual errors are inevitable, which invites the use of robotic platforms to process samples in the cPILOT strategy. Since cPILOT utilizes pH dependent tagging of the peptides, the pH needs to be maintained for the light and the heavy dimethylated set of samples. Mildly acidic-basic pH can result in dimethylation of both N-termini and lysine residues. An advantage of cPILOT is that it requires only half of the isobaric

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tags since peptide N-termini are occupied with the dimethyl groups. This affords a greater number of samples to be labelled at half the cost. Handling larger sample numbers requires that reagent exposure times are similar for the first and the last sample in a batch. A pipette dispenser that can accommodate up to 32 samples in parallel can best be achieved with the use of robotic liquid handling devices.

In order to process multiple samples by cPILOT, the manual workflow was amended to incorporate automation. The robotic liquid handler used in this study has two pods with 96-channel and 8-channel pipetting abilities, with a gripper to place the plates in the available 28 deck locations. The liquid handler is integrated with a positive pressure apparatus, orbital shaker, and a device to heat/cool samples in the 96 well plate. The positive pressure apparatus assists in performing buffer exchanges in the SPE plates during clean-up, while the orbital shaker helps to vortex/mix the samples. The robotic platform was programmed to aspirate and dispense buffers and samples to 96-well plates, incubate, vortex samples, and transfer plates. Liquids with different viscosities, such as acetonitrile and water, require specific pipetting considerations that can also be programmed into the method.

The cPILOT workflow, starting from protein quantification by BCA to labeling the peptides with isobaric tags (i.e., TMT), was performed on the liquid handler system. The complete protocol was scaled to use 96 deep well plates that can hold 2 mL per well. The buffers were prepared prior to the start of the experiment and added to the 96 well plate so as to allow parallel sample processing. In the present study, 22 workflow replicates of mouse liver homogenate were added to the deep well plates and taken through the cPILOT protocol. Finally, a single sample consisting of the 22-plex equimolar mouse liver tagged peptides was injected to the mass spectrometer. Reporter ion intensities corresponding to peptide abundances in the samples demonstrated that samples processed with the liquid handler have lower CVs than the manual protocol (data not shown). The robotic platform also greatly improved the reproducibility of sample processing. Reproducibility and robustness are very important factors while processing large numbers of samples. Pipetting errors can lead to complete mis-interpretation of the data and here the robotic platform provided low inter-sample variation. Also using the robotic platform for cPILOT reduced the time required to prepare samples. For example, after developing the automated method, it required 2.5 h to process 22 samples in comparison to 7.5 h for manual cPILOT. Experiments are on-going in our laboratory to further evaluate comparisons of the manual and automated cPILOT workflows. Based on previous reports from our laboratory, the CV%'s of protein reporter ion intensities in the manual cPILOT were on average 20% with some outliers exceeding this value¹².

cPILOT is a chemical derivatization strategy at the peptide level, that can be used for any sample type such as cells, tissues, and body fluids. cPILOT offers enhanced sample multiplexing and with the incorporation of automation can facilitate high-throughput sample multiplexing in proteomics. This throughput is necessary to further advance disease and biological understanding and biomarker discovery.

Disclosures

The authors have nothing to disclose.

Acknowledgments

The authors acknowledge Vanderbilt University Start-up Funds and NIH award (R01GM117191) to RASR.

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